

data summary

Southern Surveyor Voyage ss2013_t01



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ss2013_t01

Title

**“Oceanographic Methods training unit
(part of the Master of Marine and Antarctic Science degree program- IMAS,
University of Tasmania)”**

Principal Investigators

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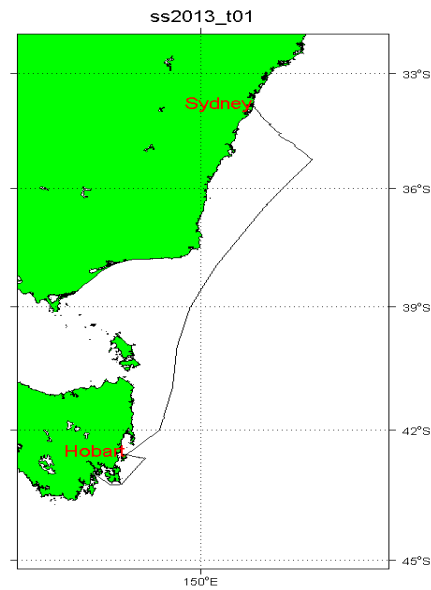
Ports

Depart: Sydney 0800hrs, Wednesday 27 February 2013
Arrive: Hobart 1100hrs, Sunday 3 March 2013

Date

26-Feb-2013 21:32:35 to 02-Mar-2013 23:09:05 (UTC)

Voyage Track



Underway Data

Navigation data is acquired using the Seapath 200 position and reference unit, which is also differentially corrected by data from the FUGRO DGPS receiver.

The Meteorological data consists of 2 relative humidity and temperature sensors; a barometer, wind sensor, and licor light sensor.

Thermosalinograph data is acquired with a Seabird TSG and remote temperature by SBE 3T. Data from a flow meter is also recorded.

Digital depth data is recorded from a Simrad EK60 sounder.

Data from “IMOS” (Integrated Marine Observing System) sensors are also included. The sensors are port and starboard radiometers and pyranometers, wind speed and direction; rain and rainrate.

See Electronics report for this voyage for instruments used and their serial numbers.

Navigation, meteorological, thermosalinograph, IMOS and depth data are preliminary quality controlled by combining all data from hourly recorded files to 5 second values in a netCDF formatted file. The combined data is referred to as “underway data”.

A combined file was made on 11 June 2013 and final by running a Java application, written by Lindsay Pender of CMAR, UwyMerger version 1.8.0 with data time range of 26-Feb-2013 21:32:35 to 02-Mar-2013 23:09:05 (UTC).

Completeness and Data Quality

Navigation data (latitude and longitude, speed over ground, ship heading and course over ground); meteorological data (port and starboard air temperature, port and starboard humidity, wind direction and speed, maximum wind gust, light, atmospheric pressure, uncorrected wind

direction, rain and speed) and IMOS data (port and starboard radiometers, port and starboard pyranometers, derived wind direction and speed, uncorrected wind direction and speed, rain and rain rate), thermosalinograph (salinity and water temperature) data were evaluated and quality controlled.

Processing Comments

A number of minor discrepancies between the port and starboard air temperature sensors were noted (max differences of about 0.3 degrees, otherwise both sensors gave very close reading with the mean absolute difference of about 0.028 degrees). These occurred usually during periods of rapid temperature increase or decrease. Investigation of these indicated that they have usually occurred when the ship was stationary with little wind or during/following periods of rainfall. This phenomenon has probably come about due to the rapid warming of the ships metal structure and air due to the ship becoming stationary or cooling of the air temperature due to the ship speeding off from stationary or due to the evaporation of rain water around the sensor housing. It is unclear as to why there should be a temperature differential between the port and starboard temperature sensors.

Major discrepancies (max differences of about 11.5%) between the port and starboard humidity sensors were observed. It should also be noted that the port humidity sensor appears to consistently give a higher reading with the mean absolute difference of about 5.37%.

As the port humidity sensor values were unusually larger than the starboard side suspect values have been NaNed with their QC flag set to {'suspect','adjusted', 'operatorFlagged'}. The non QCed original values can be found in the UWY netCDF file as rawPortHumidity.

After adjusting the port humidity values the discrepancy between the port and starboard humidity sensor improved with the max difference reduced to 3.9% and mean absolute difference reduced to 0.65%.

The courseOG values when the ship is stationary are not true values as the ship is not travelling a course however this is a feature of the current acquisition system. The QC flags have been set as good however this feature should be noted if the values during the stationary periods are to be used.

It was noted that values recorded by the IMOS port and starboard Radiometer and Pyranometer had a mean absolute difference of 2.58 and 5.93 W/m² respectively and in particular the port Radiometer values were mostly smaller than the starboard sensor.

The CTD calibration data for the primary sensor was obtained from the processed CTD file ss2013_t01012Ctd (i.e. CTD offset and scale factor 0.00097237986384939, 0.9995967086746821). This data was then used to derive the TSG salinity calibration against the calibrated CTD data. Using CTD/TSG calibration runs of ss2013_t01001Ctd.nc and ss2013_t01002Ctd.nc an averaged TSG conductivity lag of 31.0761 seconds and salinity scaling factor of 1.000064057635957 was calculated for the primary CTD conductivity cell. This was then applied to the TSG salinity data and the thermosalinograph salinity QC was set to {'good', 'manually adjusted', 'no error'}.

Note: Depth data is no longer processed. The non QCed data is available in the underway netCDF file. The QCed depth data could be obtained from the processed Swath dataset for this voyage.

Final Underway Data

The navigation, meteorological, thermosalinograph, IMOS and depth data will be entered into the CMAR divisional data warehouse. All data timestamps are in UTC.

Filename	Parameters	Resolution
ss2013_t01uwy10.csv	latitude, latitudeQC, longitude, longitudeQC, speedOG, speedOGQC, courseOG, courseOGQC, shipHeading, shipHeadingQC, uncorrWindDir, uncorrWindDirQC, uncorrWindSpeed, uncorrWindSpeedQC, waterDepth, waterDepthQC, portAirTemp, portAirTempQC, stbdAirTemp, stbdAirTempQC, portHumidity, portHumidityQC, stbdHumidity, stbdHumidityQC, windSpeed, windSpeedQC, maxWindGust, maxWindGustQC, windDir, windDirQC, PAR, PARQC, atmPressure, atmPressureQC, waterTemp, waterTempQC, salinity, salinityQC, IMOSStbdRadiometer, IMOSStbdRadiometerQC, IMOSStbdPyranometer, IMOSStbdPyranometerQC, IMOSRainRate, IMOSRainRateQC, IMOSRain, IMOSRainQC, IMOSWindSpeed, IMOSWindSpeedQC, IMOSWindDir,IMOSWindDirQC, IMOSPortRadiometer, MOSPortRadiometerQC, IMOSPortPyranometer, IMOSPortPyranometerQC, IMOSUncorrWindSpeed,MOSUncorrWindSpeedQC, IMOSUncorrWindDir,IMOSUncorrWindDirQC rain, rainQC	10 seconds
ss2013_t01uwy5min.csv	Ditto 10 second data	5 minutes

References

Subversion repository version of DPG Matlab generic tools 4077

Pender, L., 2000. Data Quality Control flags.

http://www.marine.csiro.au/datacentre/ext_docs/DataQualityControlFlags. Pdf

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