Southern Surveyor Voyage ss2012_v06
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Title
“Tectonic framework for the easternmost Coral Sea and northern extent of the Lord Howe hotspot”

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Ports
Depart: Cairns 1600hrs, Friday 26 October, 2012
Arrive: Brisbane 0800hrs, Tuesday 20 November, 2012

Date
26-Oct-2012 06:13:20 to 20-Nov-2012 02:32:05 (UTC)
**Voyage Track**

**Underway Data**
Navigation data is acquired using the Seapath 200 position and reference unit, which is also differentially corrected by data from the FUGRO DGPS receiver.

The Meteorological data consists of 2 relative humidity and temperature sensors; a barometer, wind sensor, and licor light sensor.

Thermosalinograph data is acquired with a Seabird TSG and remote temperature by SBE 3T. Data from a flow meter is also recorded.

Digital depth data is recorded from a Simrad EK60 sounder.

Data from “IMOS” (Integrated Marine Observing System) sensors are also included. The sensors are port and starboard radiometers and pyranometers, wind speed and direction; rain and rainrate.

See Electronics report for this voyage for instruments used and their serial numbers.

Navigation, meteorological, thermosalinograph, IMOS and depth data are preliminary quality controlled by combining all data from hourly recorded files to 5 second values in a netCDF formatted file. The combined data is referred to as “underway data”.

A combined file was made on 20Mar 2013 and final by running a Java application, written by Lindsay Pender of CMAR, UwyMerger version 1.8.0 with data time range of 26-Oct-2012 06:13:20 to 20-Nov-2012 02:32:05 (UTC).

**Completeness and Data Quality**
Navigation data (latitude and longitude, speed over ground, ship heading and course over ground); meteorological data (port and starboard air temperature, port and starboard humidity,
wind direction and speed, maximum wind gust, light, atmospheric pressure, uncorrected wind
direction, rain and speed) and IMOS data (port and starboard radiometers, port and starboard
pyranometers, derived wind direction and speed, uncorrected wind direction and speed, rain
and rain rate), thermosalinograph (salinity and water temperature) data were evaluated and
quality controlled.

**Processing Comments**

A number of minor discrepancies between the port and starboard air temperature sensors were
noted (max differences of about 1.85 degrees, otherwise both sensors gave very close reading
with the mean absolute difference of about 0.032 degrees). These occurred usually during
periods of rapid temperature increase or decrease. Investigation of these indicated that they
have usually occurred when the ship was stationary with little wind or during/following
periods of rainfall. This phenomenon has probably come about due to the rapid warming of
the ships metal structure and air due to the ship becoming stationary or cooling of the air
temperature due to the ship speeding off from stationary or due to the evaporation of rain
water around the sensor housing. It is unclear as to why there should be a notable temperature
differential between the port and starboard temperature sensors.

A similar discrepancy (max differences of about 14.7%) between the port and starboard
humidity sensors was observed. It should also be noted that the port humidity sensor appears
to give a higher reading with the mean absolute difference of about 3.42%. The recorded
values are within instrument tolerance.

The courseOG values when the ship is stationary are not true values as the ship is not
travelling a course however this is a feature of the current acquisition system. The QC flags
have been set as good however this feature should be noted if the values during the stationary
periods are to be used.

The optical rain gauge was not functional during this voyage. Therefore the recorded zero
values for 'IMOSRain', 'IMOSRainRate have been NaNed and their QC flags set to
{‘bad’, ‘none’, ‘operatorFlagged’}.

It was noted that values recorded by the IMOS port and starboard Radiometer and
Pyranometer had a mean absolute difference of 2.8 and 10.75 W/m$^2$ respectively and in
particular the port Radiometer values were mostly smaller than the starboard sensor.

No hydrology was undertaken for this voyage therefore, the CTD calibration data for the
primary sensor was obtained from the previous voyage ss2012_t07 (i.e. CTD offset and scale
factor 0.00729476437793863, 0.998302706260003). This data was then used to derive the
TSG salinity calibration against the calibrated CTD data. Using CTD/TSG calibration run in
the CTD deployments ss2012_v06tsgcal001Ctd.nc with a TSG conductivity lag of 32
seconds, a salinity scaling factor of 1.000363935002681 was calculated for the primary CTD
conductivity cell. This scaling factor along with the lag of 32 seconds was applied to the TSG
salinity data and the thermosalinograph salinity QC was set to {‘good’, ‘manually adjusted’, ‘no
error’}.
Note: Depth data is no longer processed, however, non QCed data is still available in the underway data set. QCed depth data can be obtained from processed Swath dataset for this voyage.

**Final Underway Data**

The navigation, meteorological, thermosalinograph, IMOS and depth data will be entered into the CMAR divisional data warehouse. All data timestamps are in UTC.

### Filename Parameters Resolution

<table>
<thead>
<tr>
<th>Filename</th>
<th>Parameters</th>
<th>Resolution</th>
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<td>ss2012_v06uwy5min.csv</td>
<td>Ditto 10 second data</td>
<td>5 minutes</td>
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**References**

Subversion repository version of DPG Matlab generic tools 3974  

Processed by: A Sarraf , CSIRO Marine and Atmospheric Research, Hobart, Tasmania, Australia