

RV *Investigator*

CTD Processing Report

Voyage #:	ge #: IN2017_V04	
Voyage title: The whole enchilada: from production to predation in Tax Sea ecosystems		
Depart:	1400 Brisbane, Thursday, 31 August 2017	
Return:	1000 Sydney, Monday, 18 September 2017	
Report compiled by:	Karl Malakoff	





Contents

1	Sun	nmary	3
	1.1	Voyage Title	3
	1.2	Principal Investigators	3
	1.3	Voyage Objectives	3
	1.4	Area of operation	4
2	Pro	cessing Notes	5
	2.1	Background Information	5
	2.2	Pressure reference	6
	2.3	Conductivity Calibration	7
	2.4	Dissolved Oxygen Sensor Calibration	10
	2.4.	1 Results	10
	2.5	Other sensors	13
	2.6	Bad data detection	13
	2.7	Averaging	14
3	Ref	erences	14

1 Summary

These notes relate to the production of quality controlled, calibrated CTD data from RV Investigator voyage in 2017_v04, from 31 Aug 2017 – 18 Sep 2017.

Data for 38 deployments were acquired using the Seabird SBE911 CTD unit 21 fitted with 36 twelve litre bottles on the rosette sampler. Cast 3 was aborted on deck and contains no valid data. Samples were collected on cast 2 and casts 4-38. Sea-Bird-supplied and CSIRO calibration factors were used to compute the pressures, preliminary conductivity oxygen and temperature data. The data were subjected to automated QC to remove spikes and out-of-range values.

The final conductivity calibration was based on one deployment grouping. The primary sensor had a standard deviation of 0.0012186. The secondary sensor had a standard deviation of 0.0011728. Both sensors had a standard deviation (S.D) less than our target of 'better than 0.002 PSU'.

The final oxygen calibration from the primary sensor had a standard deviation of 0.61387uM. The final oxygen calibration for the secondary sensor had a standard deviation of 0.56887. The agreement between the sensor and bottle data was good for both sensors. Both Oxygen sensors calibrated closely.

A Biospherical photosynthetically active radiation (PAR), Wetlabs transmissometer and Chelsea fluorometer sensors were also installed on the auxiliary A/D channels of the CTD.

Voyage Details

1.1 Voyage Title

The whole enchilada: from production to predation in Tasman Sea ecosystems.

1.2 Principal Investigators

The Chief Scientist on board was Iain Suthers from UNSW/SIMS.

1.3 Voyage Objectives

For details on the objectives of the voyage, refer to the Voyage Plan and/or summary which can be viewed on the <u>CSIRO MNF web site</u>.

1.4 Area of operation

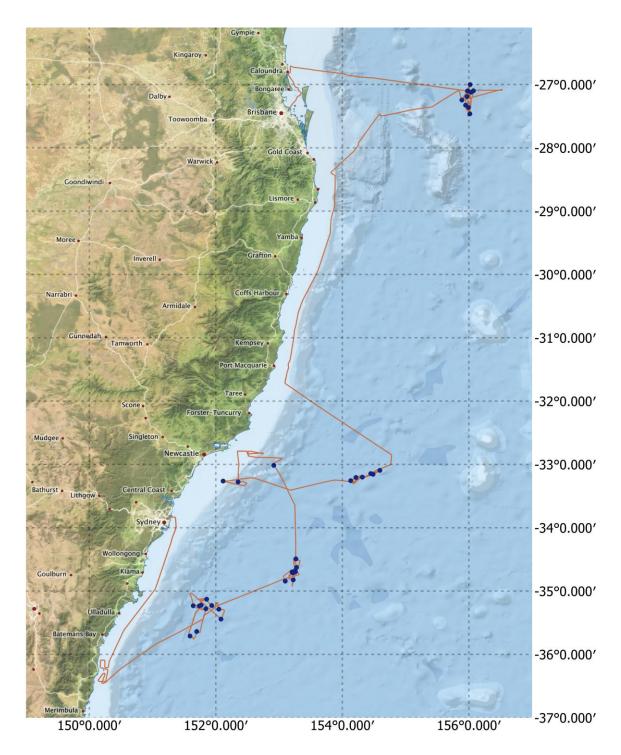


Figure 1. Area of Operation for in2017_v04 CTDs

2 Processing Notes

2.1 Background Information

The data for this voyage were acquired with CTD SBE9+ unit 21 with dual conductivity and temperature sensors.

There were 38 deployments for this voyage as shown on Figure 1.

Rapp Hydema heave compensation was used on the CTD winch for all casts.

A Biospherical photosynthetically active radiation (PAR), Wetlabs transmissometer and Chelsea Flourometer sensors were also installed on the auxiliary A/D channels of the CTD. These sensors are described in Table 1 below.

Unit	Data Channel	SBE9 Connector	Model	Serial Number
CTD 21			SBE9+ V_2	1312
Deck Unit			SBE11 V_2	0513
Primary Temperature		JB1	SBE3T	6189
Primary Conductivity		JB2	SBE4C	4685
Secondary Temperature		JB4	SBE3T	4722
Secondary Conductivity		JB5	SBE4C	4664
Primary Pump		JB3	SBE5	8344
Secondary Pump		JB3	SBE5	8345
Primary Oxygen	A0	JT2	SBE43	3534
Secondary Oxygen	A1	JT2	SBE43	3159
Altimeter	A2	JT3	PA 500	05301.228403
PAR	A3	JT3	QCP-2300-HP	70111
Fluorometer Chelsea Aquatracker	A4	JT5	Chlorophyll –a Aquatracka III – 430/685nm	06-5941-001
Transmissometer	A5	JT5	Wetlabs CSTAR 25cm	1421DRT
MNF IMU	Serial	JT4	SITIMU007	#01

Table 1. CTD Sensor configuration for in2017_v04 CTDs

There were 38 CTD casts. Cast 3 was aborted on deck and has no data or samples. No samples were collected for cast 3. For the remaining casts water samples were collected using a Seabird SBE9+ 36-bottle rosette sampler with twelve litre bottles fitted to the frame.

The raw CTD data was acquired using an SBE9/11+ and recorded to netCDF scan files by the CAP Java application.

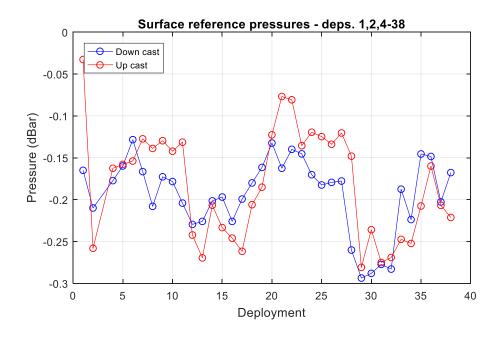
The netCDF files were processed using CapPro v2.9. This Matlab software was used to apply automated QC and preliminary processing to the data. This included spike removal, identification of

water entry and exit times and the determination of the pressure offsets. The automatically determined pressure offsets and in-water points were inspected and adjusted where necessary. The hydrology data were loaded and CapPro computed the matching CTD sample burst data.

The bottle sample data were used to compute final conductivity and dissolved oxygen calibrations. These were applied to the data and binned 1dB averaged data files were produced.

2.2 Pressure reference

The surface pressure offsets are plotted in Figure 2 below. The blue circles refer to initial out-of-water values and the red circles the final out-of-water values.



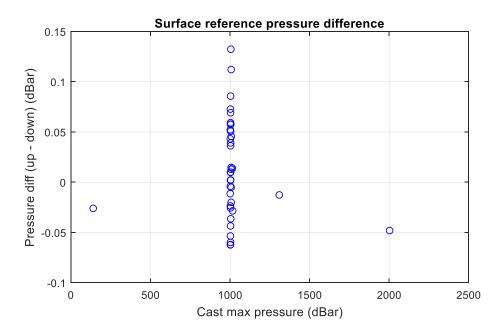
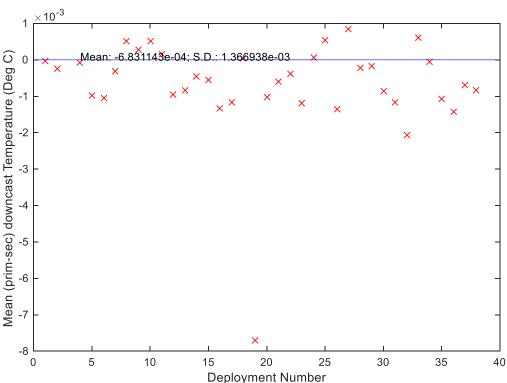


Figure 2. CTD pressure reference

The mean difference between the primary and secondary temperature sensors is plotted below. Most deployments should plot within ±1 m°C. Figure 3 indicates neither sensor has drifted significantly from its calibration.



Mean difference, Temperature sensors, |dT/dP| < 0.3 °C/dbar, RV Investigator, in2017,04

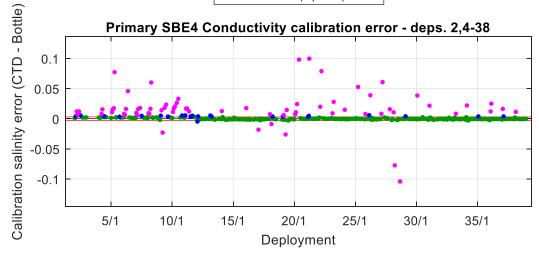
Figure 3. Temperature sensor difference

2.3 Conductivity Calibration

Discrepancies and possible sampling problems between bottle and CTD salinities for the primary conductivity sensor would show in Figure 4, the plot of calibrated (CTD - Bottle) salinity below. The primary conductivity calibration was based upon the sample data for 257 of the total of 327 samples, which meets our target of 75%. The secondary conductivity calibration was based upon sample data for 257 of the 327 samples also meeting out target of 75%.

The outliers marked in the figures below with magenta dots are excluded from the calibration, the outliers marked with blue dots are used in the calibration but are weighted based on their distance from the mean. Any outliers marked with red crosses or dots are also excluded from the calibration.

- Good (234 points)
- + Bad (op) Hydro (0 points)
- Suspect CTD (23 points)
- Bad (soft) CTD (70 points)
- Bad CTD (0 points)



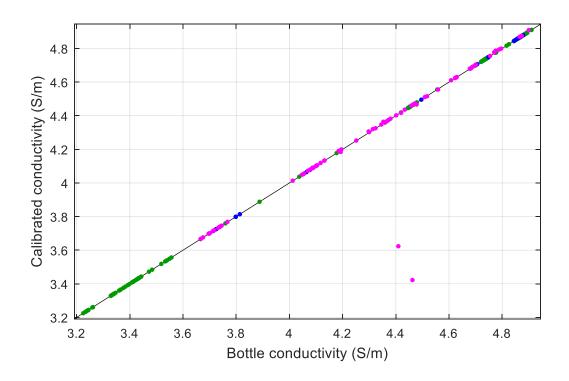
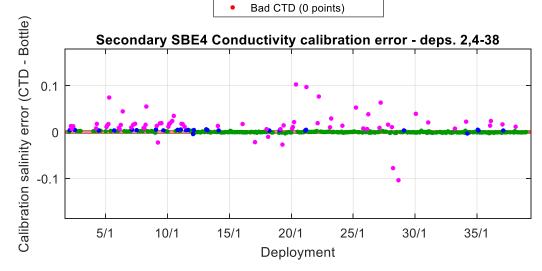


Figure 4. Primary conductivity calibrations

- Good (231 points)
- + Bad (op) Hydro (0 points)
- Suspect CTD (26 points)
- Bad (soft) CTD (70 points)



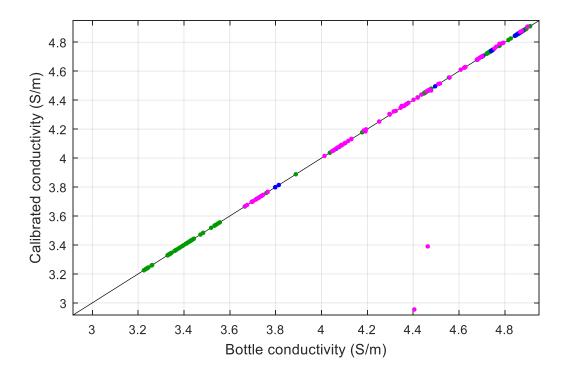


Figure 5. Secondary conductivity calibrations

The final result for the primary conductivity sensor was -

Cutoff 0.003

Scale Factor (a1) 1 wrt. Manufacturer's calibration

Offset (a0) 0.0015352 ditto

Calibration S.D. (Sal) 0.0012186 PSU

The calibration using the secondary conductivity sensor was -

Scale Factor (a1) 0.9999 wrt. Manufacturer's calibration

Offset (a0) 0.00039726 ditto

Calibration S.D. (Sal) 0.0011728 PSU

Calibration standard deviation is the standard deviation of the difference between the calibrated values and the bottle values. This calibration is within the range we normally aim for, an S.D. of 0.002 psu or lower for 'typical' oceanographic voyages. The above calibration factors were applied to deployments 1 to 38.

Data from the primary conductivity and temperature sensors were used to produce the averaged salinities.

2.4 Dissolved Oxygen Sensor Calibration

Sea-Bird (2013) describes the SBE43 as "a polarographic membrane oxygen sensor having a single output signal of 0 to +5 volts, which is proportional to the temperature-compensated current flow occurring when oxygen is reacted inside the membrane. A Sea-Bird CTD that is equipped with an SBE43 oxygen sensor records this voltage for later conversion to oxygen concentration, using a modified version of the algorithm by Owens and Millard (1985)".

Calibration involves performing a linear regression, as per Sea-Bird (2012) to produce new estimates of the calibration coefficients Soc and Voffset. These new coefficients are used, along with the other, manufacturer-supplied coefficients, to derive oxygen concentrations from the sensor voltages.

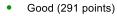
2.4.1 Results

Deeper casts (>1000m) are known to be affected by pressure-induced hysteresis with this sensor. This is corrected automatically within CapPro using the method discussed by Sea-Bird (2014).

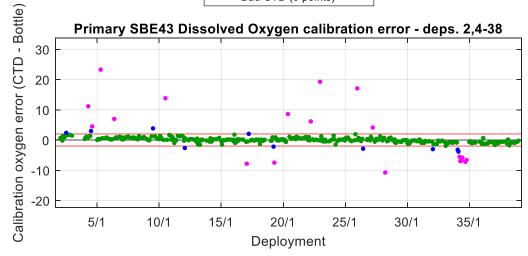
There is a small mismatch between downcast and upcast dissolved oxygen due to the response time of the sensor. No correction for the sensor lag effect has been applied.

The plots below are of CTD - bottle oxygen differences for both upcast and downcast data (red indicates 'bad' data).

A single calibration group for both the primary and secondary sensor was used with the associated SBE43 up-cast data to compute the new Soc and Voffset coefficients. This is shown in Figures 6 and 7.



- + Bad (op) Hydro (3 points)
- Suspect CTD (10 points)
- Bad (soft) CTD (19 points)
- Bad CTD (0 points)



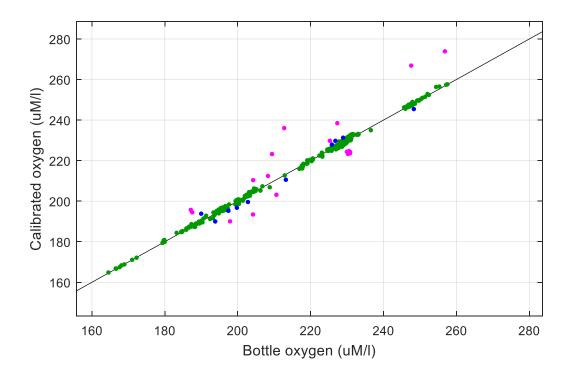
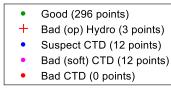
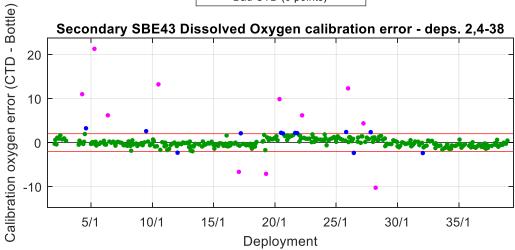


Figure 6. Dissolved Oxygen calibration, deployments 2,4-38 – primary sensor





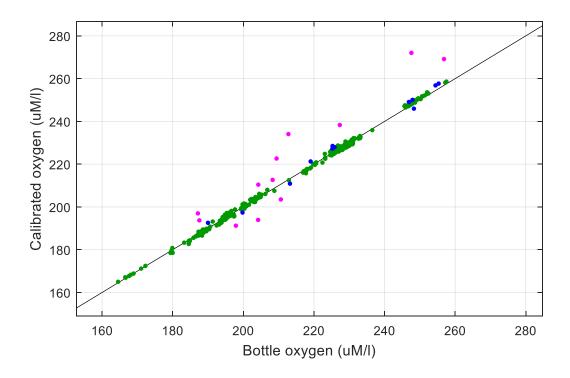


Figure 7. Dissolved Oxygen calibration, deployments 2,4-38 – secondary sensor

The old and new Soc and Voffset values for DO sensors are listed in Table 2 below. The Soc value is a linear slope scaling coefficient; Voffset is the fixed sensor voltage at zero oxygen. The calibration was applied for deployments 6 and 7 for the primary sensor. The final secondary sensor calibration was applied to all deployments. The averaged files were created using the result from the secondary sensor.

Calibration	April 2017 Seabird	primary sensor	March 2017 CSIRO	secondary
Voffset	-4.979e-01	-4.9253e-01	-5.0737e-01	-5.9742e-01
Soc	4.754e-01	4.9512e-01	5.8453e-01	5.6887e-01
Fit SD (uM)		0.61387		0.56887

Table 2. Dissolved Oxygen calibration

2.5 Other sensors

The C-Star transmissometer was used on all deployments. It was calibrated to give a nominal output of 0-100 fsd (full scale deflection).

A Chelsea fluorometer were both used for all deployments. It was calibrated to give a nominal output of 0-100% of the full scale measurement of the instrument.

The Biospherical PAR sensor was also used for all deployments. The output is a nominal 0-5 volts. This data channel has been included in the output files for all deployments. Clearly, time of day and environmental factors such as sea state and cloud cover impact on these readings. If most or all of the values for a deployment are near zero it indicates a night-time cast. In deployments where the PAR profiles have sub-surface maxima the CTD may have been shaded by the ship.

2.6 Bad data detection

The limits for each sensor are configured in the CAP CTD acquisition software and are written to the netCDF scan file. Typical limits used for the sensor range and maximum second difference are in Table 3 below. The rejection rate is recorded in the CapPro processing log file.

Sensor	Range min	Range max	Max Second Diff
temperature	-2	40	0.05
conductivity	-0.01	7	0.01
oxygen	-0.1	500	0.5
fluorometer	0	100	0.5

Table 3. Sensor limits for bad data detection

2.7 Averaging

The calibrated data were 'filtered' to remove pressure reversals and binned into the standard product of 1dbar averaged netCDF files. The binned values were calculated by applying a linear, least-squares fit as a function of pressure to the sensor data for each bin, using this to interpolate the value for the bin mid-point. This method is used to avoid possible biases which would result from averaging with respect to time.

Each binned parameter is assigned a QC flag. Our quality control flagging scheme is described in Pender (2000).

The QC Flag for each bin is estimated from the values for the bin components. The QC Flag for derived quantities, such as Salinity and Dissolved Oxygen are taken to be the worst of the estimates for the parameters from which they are derived.

3 References

Beattie, R.D., 2010: procCTD CTD Processing Procedures Manual.

http://www.marine.csiro.au/~dpg/opsDocs/procCTD.pdf.

Suthers, I., 2017: The RV Investigator. Voyage Plan in 2017_v04 -

hhttp://mnf.csiro.au/~/media/Files/Voyage-plans-and-

<u>summaries/Investigator/Voyage%20Plans%20summaries/2017/IN2017_V04%20Voyage%20Plan-FINAL.ashx</u>

Pender, L., 2000: Data Quality Control Flags.

http://www.cmar.csiro.au/datacentre/ext_docs/DataQualityControlFlags.pdf

Sea-Bird Electronics Inc., 2013: Application Note No 64: SBE 43 Dissolved Oxygen Sensor -- Background Information, Deployment Recommendations, and Cleaning and Storage. http://www.seabird.com/document/an64-sbe-43-dissolved-oxygen-sensor-background-information-deployment-recommendations

Sea-Bird Electronics Inc., 2012: Application Note No 64-2: SBE 43 Dissolved Oxygen Sensor Calibration and data Corrections.

http://www.seabird.com/document/an64-2-sbe-43-dissolved-oxygen-sensor-calibration-and-data-corrections

Sea-Bird Electronics Inc., 2014: Application Note No 64-3: SBE 43 Dissolved Oxygen (DO) Sensor - Hysteresis Corrections.

http://www.seabird.com/document/an64-3-sbe-43-dissolved-oxygen-do-sensor-hysteresis-corrections