

# Webb Research Corporation

82 Technology Park Drive, E. Falmouth, MA 02536-4441 (508) 548-2077 FAX (508) 540-1686

## USER MANUAL – APEX-SBE PROFILER

APEX-SBE INSTRUMENTS

Serial # 1845

REV DATE: 11-16-04  
WRC Job no. 1046 CSIRO  
Software Rev 11-04-04  
**Park and Profile with 28-bit ID with ice detection  
And optional Aanderaa sensor**

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## I. ALKALINE BATTERY WARNING

The profiler contains alkaline "D" cells.

There is a small but finite possibility that batteries of alkaline cells will release a combustible gas mixture. This gas release generally is not evident when batteries are exposed to the atmosphere, as the gases are dispersed and diluted to a safe level. When the batteries are confined in a sealed instrument mechanism, the gases can accumulate and an explosion is possible.

Webb Research Corp. has added a catalyst inside of these instruments to recombine Hydrogen and Oxygen into H<sub>2</sub>O, and the instrument has been designed to relieve excessive internal pressure buildup by having the upper end cap release.

Webb Research Corp. knows of no way to completely eliminate this hazard. The user is warned, and must accept and deal with this risk in order to use this instrument safely as so provided. Personnel with knowledge and training to deal with this risk should seal or operate the instrument. Webb Research Corp. disclaims liability for any consequences of combustion or explosion.

## II. Reset and Self Test

Profilers are shipped to the deployment site in Hibernate mode. Shortly before deployment, reset the profiler by passing a magnet over the marked location on the pressure case. The profiler will run a self-test, transmit for 6 hours with the bladder extended, and then begin its pre-programmed mission.

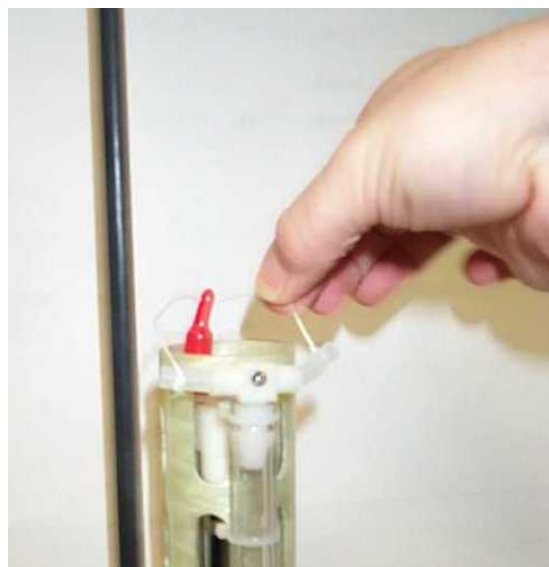
The six ARGOS transmissions during self-test and the transmissions during the initial 6 hour period contain data about the instrument and are outlined in (V) ARGOS DATA, part (C) TEST MESSAGE FORMAT.

### Procedure:

1. Secure float in horizontal position, using foam cradles from crate.



**IMPORTANT:**  
Remove plastic bag  
and three plugs from  
CTD sensor, if they  
have not already been  
removed.





2. Minimum temperature  $-2$  deg C. If necessary, let float warm indoors before proceeding.
3. Carefully remove black rubber plug from bottom center of yellow cowling to verify bladder inflation (per below). **Use fingers only- tools may puncture bladder. Be sure to replace plug before deployment.**

Note: it can be very difficult to replace plug when air bladder is fully inflated. Replace plug during beginning of air bladder inflation.

Purpose of plug is to prevent silt entry if float contacts sea floor.

4. Hold provided magnet at RESET position marked on for several seconds, then remove magnet.

Note: Magnetic switch must be activated (held) for at least one second to reset the instrument. (This is to provide a safety against accidental reset during transport.) **Thus, if the float does not respond as below, the instrument was probably not reset.**

5. The air pump will operate for 1 second.
6. The PTT will transmit 6 times at 6 second intervals. Place ARGOS receiver/beeper close to antenna to detect transmissions.
7. The piston pump will begin to operate. The piston will move to the retracted Storage Position, if not already there, pause 2 seconds and then move to full extension.
8. The oil bladder will expand, this should take 15 - 25 minutes.
9. After the piston pump stops, PTT will transmit at specified ARGOS rate.
10. At every PTT transmission, the air pump will turn on for 6 seconds until the air portion of the bladder has been inflated. The pump should turn on 8 – 10 times.
11. 6 hours after reset, transmissions will cease, the bladder will deflate, and the piston pump will retract, the profiler begins its programmed mission.
12. Reminder - replace black rubber plug in cowling hole before deployment.

During self-test, the controller checks the internal vacuum sensor. If the internal pressure has increased above a preset limit (i.e. hull leakage caused loss of vacuum), the instrument will not pump. **If you do not detect the 6 test transmissions, and if the bladder does not inflate, then the self-test has failed and the instrument should not be deployed!**

### III. System Description –

#### A. Ice detection feature

1) The median of 7 near-surface temperature points (50, 45, 40, 35, 30, 25, 20 db) is calculated. If the median is less than  $-1.79\text{ C}$ , there is a high probability of ice, so ascent is aborted, and the profile data are discarded. The next profile will occur on the same schedule, and the profile number (byte 06 of message one) will increment for each ascent, regardless of whether or not the abort occurs. If a profile has been aborted due to ice detection byte 18 of message one will increment by one for each occurrence.

2) If ASCEND TIME (P9) expires before pressure has reached the surface pressure, and current  $T < -1.79\text{ C}$  (one sample) then abort. If  $T > -1.79\text{ C}$ , the float will go to maximum buoyancy condition and attempt to surface.

Ascend time is typically set to 150-200% of expected time required for ascent at  $0.08\text{ m/s}$ . A standard float goes to maximum buoyancy when ascend time expires. This feature is intended to ensure that the float reaches the surface in locations with unusual near-surface stratification.

#### B. B. Optional Aanderaa Oxygen Sensor

In addition to SeaBird model 41 CTD sensor, these APEX carry the (optional) Aanderaa Oxygen Optode 3830. All sensors are mounted to the upper end-cap. The oxygen sensor communicates with the APEX controller via RS-232C interface, and provides absolute oxygen content in micro molar ( $\mu\text{M}$ ), as well as temperature. Relative air saturation (%) is not returned.

Note: both the CTD and optode provide temperature data.

Terminology: in this manual, temperature from the SeaBird (SBE) CTD is designated SBE temperature, while temperature from the optode is  $T_{\text{optode}}$ .

Oxygen content is designated  $O_2\text{conc}$ .

$O_2\text{conc}$  and  $T_{\text{optode}}$  are sampled:

- during upcast profile whenever CTD is sampled per depth table

NOTE re handling: do not lift or pull on the oxygen optode.

## IV. Deployment

- RESET instrument.
- SELF-TEST starts automatically (see above).
- When piston pump stops, air pump inflates, external bladder is full, PTT will transmit for 6 hours at ARGOS Repetition rate intervals. Typical repetition rate is 90 seconds or less. Programmed repetition rate can be found in the Missions section of this manual.
- If the repetition rate is 120 seconds the controller is not communicating properly with the CTD and the float should not be deployed.
- Six hours after reset, the piston pump will retract and bladder will deflate. Deploy before this time is up or reset the instrument again to re-initialize the 6 hour period. The purpose is to have the instrument on the surface and receive test transmissions.
- Pass a rope through the hole in the damper plate.
- Holding both ends of doubled up rope, carefully lower the float into the water. Do not let rope slide through hole in disk- this may cut the plastic disk.
- Take care not to damage the antenna.
- Do **not** leave the rope with the instrument, release one end and retrieve the rope.
- The float will remain on the surface until the 6 hour interval has expired.

## v. PARK and PROFILE Feature

**APEX floats with park and profile feature can be set to profile from a maximum depth (profile depth) after a given number of profiles from a shallower depth (park depth).**

Terminology:

**PARK:** intermediate depth at which the float drifts

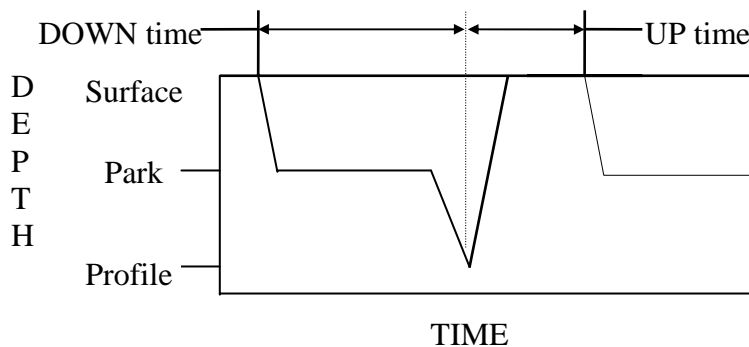
**PROFILE:** maximum depth to which the float descends before profiling up.

**DOWN time:** spent during descent and at park depth.

**UP time:** includes ascent and time at surface.

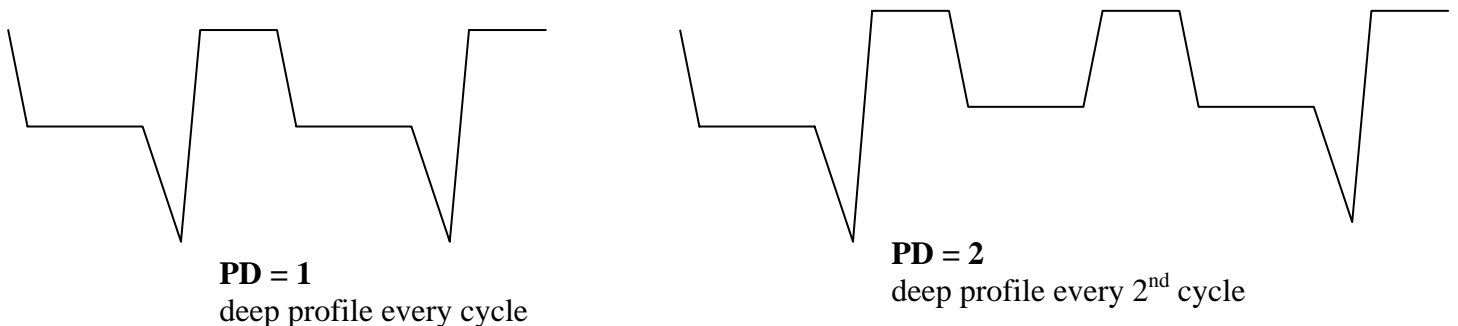
Ascent rate: approximately .08 meters per second.

Total Up time is typically set to 12 to 20 hours, increasing proportional to depth and amount of data to be transmitted per profile. Another factor is deployment location: due to the polar orbit of ARGOS, the number of passes per day increases at high latitudes.



Parameter **PD** determines the frequency of deep profiles.

Schematic examples:



## **VI. ARGOS DATA**

### **A. SERVICE ARGOS PARAMETERS**

The user must specify various options to Service ARGOS. These choices depend on how the user wishes to receive and process data. Typical parameters are listed below:

- Standard location.
- Processing: Type A2 (pure binary input; hexadecimal output)
- Results Format: DS (all results from each satellite pass), Uncompressed.
- Distribution Strategy: Scheduled, all results, every 24 hours.
- Number of bytes transmitted: 31 per message\*

Note: Webb Research strongly recommends all users to use ARGOS “Multi Satellite Service”, which provides receptions from 3 satellites instead of 2 for a small incremental cost.

\* Using Argos 28-bit ID Format, 31 data bytes are transmitted in each message. With 20-bit ID Format, each message had 32 data bytes. (see Appendix D for more information).

## **B. DATA FORMAT – 31 For 28-bit ID format Aanderaa and Ice detect**

Data are sent via ARGOS in 31 byte hex messages. The number of 31 byte messages sent depends on the programmed quantity of temperature measurements per profile. See appendix D

Format for message number 1 only:

Byte #

- 01 **CRC**, described in section C.
- 02 **Message number**, Assigned sequentially to each 32 byte message (Total number of messages per profile is shown below). Messages are transmitted in sequential order starting with 1 and incrementing by one for the data set.
- 03 **Message block number**, begins as 1 and increments by one for every ARGOS message data set. This, combined with the ARGOS repetition rate (section VI), allows the user to track surface drift. Byte 03 will roll-over at 256 and will reset to 1 on each new profile.
- 04 & 05 **Serial number**, identifies the controller board number. (This may not be the same as instrument number.)
- 06 **Profile number**, begins with 1 and increases by one for every float ascent.
- 07 **Profile length**, is the number of six byte STD measurements in the profile. Total number of bytes of STD data from each profile depends on the sampling strategy chosen.
- 08 **Profile termination flag byte 2** -see section D
- 09 **Piston position**, recorded as the instrument reaches the surface.
- 10 **Format Number** (identifier for message one type)
- 11 **Depth Table Number** (identifier for profile sampling depths)
- 12 & 13 **Pump motor time**, in two second intervals. (multiply by 2 for seconds)
- 14 **Battery voltage**, at initial pump extension completion
- 15 **Battery current**, at initial pump extension completion, one count = 13 mA
- 16 **Profile piston position** (*park and profile floats only*)
- 17 **Ice detection count** - increments by one for each aborted profile
- 18 **Air bladder pressure** measured in counts - approximately 148 counts
- 19 & 20 **Park temperature**, sampled just before instrument descends to target depth.
- 21 & 22 **Park salinity**, sampled just before instrument descends to target depth.
- 23 & 24 **Park pressure**, sampled just before instrument descends to target depth.
- 25 & 26 **Aanderaa O<sub>2</sub>conc** sampled just before instrument descends to target depth.
- 27 & 28 **Aanderaa T<sub>optode</sub>** sampled just before instrument descends to target depth.
- 29 **Park battery voltage**, no load
- 30 **Park battery current**
- 31 **Surface Pressure**, 1<sup>st</sup> half of two byte measurement. Second byte appears in byte 3 of message 2\*\*



Format for message number 2:

Byte #

- 01 **CRC**, described in section C.
- 02 **Message number**
- 03 **Surface Pressure, 2nd** half of two byte measurement as recorded just before last descent with an offset of +5 dbar\*\*
- 04 **Internal vacuum** measured in counts- approximately 101 counts
- 05 **Park piston position**
- 06 **SBE pump Voltage**
- 07 **SBE pump current**
- 08 to 31 10 bytes- **in sequence and continuing into following messages\*\***
- - 2 bytes **temperature**
  - 2 bytes **salinity**
  - 2 bytes **pressure**
  - 2 bytes **O<sub>2</sub>conc**
  - 2 bytes **T<sub>optode</sub>**

\*\*Note byte pairs will split between messages. For instance byte 31 of message #1 will contain half of the byte pair for the surface pressure. The other half byte pair will appear in byte 3 of message #2.

Sampling continues as shown above relevant to the number of depth table points sampled. After the last data point in last message a Hex value of FFFF will fill remaining bytes.

APEX records a profile during ascent (ie upcast). Bottom pressure may change due to several causes, such variation of insitu density, internal waves, float grounding in shallows, change of float mass, etc. APEX automatic depth adjustment will compensate in most, but not all, cases.

Format for message number 3 and higher

Byte #

- 01 **CRC**, described in section C.
- 02 **Message number**
- 3-31 In 10 byte per depth table measure sequence describe above.

The number of sample points taken is proportional to depth, as per sample depth table below. The first (i.e. deepest) sample is taken at the first point in the depth table above bottom pressure.

**Depth Table No 38**

Sample point	Pressure dbar	Sample point	Pressure dbar	Sample point	Pressure dbar
	Bottom				
1	2000	27	340	53	90
2	1900	28	330	54	85
3	1800	29	320	55	80
4	1700	30	310	56	75
5	1600	31	300	57	70
6	1500	32	290	58	65
7	1400	33	280	59	60
8	1300	34	270	60	55
9	1200	35	260	61	50
10	1100	36	250	62	45
11	1000	37	240	63	40
12	900	38	230	64	35
13	800	39	220	65	30
14	700	40	210	66	25
15	650	41	200	67	20
16	600	42	190	68	15
17	550	43	180	69	10
18	500	44	170	70	7
19	480	45	160	71	*4 or surf
20	460	46	150		
21	440	47	140		
22	420	48	130		
23	400	49	120		
24	380	50	110		
25	360	51	100		
26	350	52	95		

\* The SeaBird CTD is not sampled at zero pressure, to avoid pumping the cell dry and/or ingesting surface oil slicks. The shallowest profile point is taken at either 4 dbar or at the last recorded surface pressure plus 5 dbar, whichever value is larger.

### C. TEST MESSAGE FORMAT

The test message is sent whenever an **I2** command is given, the six transmissions during the startup cycle, and during the six hour surface mode period prior to the first dive. Each test message has 31 Bytes, in hex unless otherwise noted, with the following format:

Byte #

- 01 **CRC**, described in section C.
- 02 **Message block number**, begins as 1 and increments by one for every ARGOS message.
- 03 & 04 **Serial number**, identifies the controller board number. (This may not be the same as instrument number.)
- 05 & 06 **Time from start up**, in two second intervals (Hex)
- 07 **Flag (2) byte**
- 08 & 09 **Current pressure**, in bar
- 10 **Battery voltage**
- 11 **Current Bladder pressure**, in counts
- 12 **Flag (1) Byte**
- 13 **Up time**, in hours
- 14 & 15 **Down time**, in hours
- 16 & 17 **Park pressure**, in bar
- 18 **Park piston position**, in counts
- 19 **Depth correction factor**, in counts
- 20 **Storage piston position**, in counts
- 21 **Fully extended piston position**, in counts
- 22 **OK vacuum count at launch**, in counts
- 23 **Ascend time**, in intervals
- 24 **Target bladder pressure**, in counts
- 25 & 26 **Profile pressure**, in bar
- 27 **Profile piston position**, in counts
- 28 **Deep profile cycle counts**
- 29 **Month**, software version number (in decimal).
- 30 **Day**, software version number (in decimal).
- 31 **Year**, software version number (in decimal).

- \* Flag (2) byte:
- 1 Deep profile
  - 2 Pressure reached zero
  - 3 25 minute Next Pressure timeout
  - 4 piston fully extended before surface
  - 5 Ascend time out
  - 6 Test message at turn on
  - 7 Six hour surface message
  - 8 Seabird String length error

- \*\*Flag (1) byte:
- 1 Trip interval time
  - 2 Profile in progress
  - 3 Timer done
  - 4 UP/ DOWN
  - 5 Data entry error
  - 6 Measure battery
  - 7 Piston motor running
  - 8 Negative SBE number

#### D. Telemetry error-checking (CRC)

Because ARGOS data contains transmission errors, the first byte of each message contains an error checking value. This value is a Cyclic Redundancy Check (CRC), and is calculated as a function of the message content (bytes 2 to 32).

- For each message, calculate a CRC value
- Compare the calculated CRC to the transmitted CRC (byte no. 2)
- If the calculated and transmitted CRC values are not equal, the message has been corrupted and should be deleted before further data processing.

Appendix (B) lists a sample program (in BASIC) to calculate the CRC value for a message. This program can be provided upon request in Basic, Fortran or C

#### E. Conversion from hexadecimal to useful units

The pressure is measured every 6 seconds. Temperature, salinity and pressure are measured and stored at each point in the depth table. Two hex bytes are stored for each sensor. The decimal numbers from the STD sensors are converted to hex for compression in the ARGOS transmission as follows:

Temperature: 5 digits, 1 milli-degree resolution.  
Salinity: 5 digits, .001 resolution  
Pressure: 5 digits, 10 cm resolution.

To convert the hex ARGOS message back to decimal numbers:

	hex	→	dec	=	converted	units
Temperature:	3EA6	→	16038	=	16.038	C
Temperature*:	F58B	→	02677	=	-2.677	C
Salinity**:	8FDD	→	36829	=	36.829	
Pressure:	1D4C	→	7500	=	750.0	decibars
Current:	0A	→	10	=	130	mA
Volts:	99	→	153	=	15.7	volts
Correlation time:	03DE	→	990	=	304.425	Seconds
O <sub>2</sub> conc	612f	→	24879	=	248.79	absolute O <sub>2</sub> conc (µM)
T <sub>optode</sub>	929	→	2345	=	23.45	C

Voltage (V) = counts/10 + .4 (counts is in decimal number) nominally 15 V and decreasing.

Current (mA) = counts \*13 (counts is in decimal number)

Vacuum (inHg) = counts \*-0.209 + 26.23 (counts is in decimal number) nominally 5 inHg.

\*Note regarding negative temperatures ( T °C < 0 )

Positive temperature range is 0 to 62.535C (0 to F447 hex)

Negative temperature range is -0.001 to -3.000C (FFFF to F448 hex).

If (hex value) ≥ F448, then compute FFFF - (hex value) = Y

Convert Y to decimal = dec\_Y

(dec\_Y + 1) / 1000\*-1 = degrees C

\*\*The 5 most significant salinity digits are telemetered. The 6 digit salinity number is rounded up and converted to hex. 36.8286 rounds to 36.829 and converts to 8FDD.

## VII.

This section lists the parameters for each float covered by this manual.  
The parameter listing appears when the float is RESET while connected to a terminal.

### **INSTRUMENT # 1845**

APEX version 11 04 04 sn 2183 031 038

78254BE ARGOS ID number

044 seconds rep rate

225 hours DOWN

015 hours UP

1000 d-bar park pressure P1

085 park piston position P2

012 ascent rate correction P3

022 storage piston position P4

248 piston full extension P5

2000 d-bar profile pressure P6

025 profile piston position P7

115 OK vacuum count P8

009 ascend time intervals P9

145 air bladder pressure PB

001 deep profile count PD

025 Initial piston extension

## Appendix A: Flag Byte Description

Two memory bytes are used, one bit at a time, to store 16 different bits of program flow information. Both of these bytes are telemetered in the test messages sent at startup and for the initial 6 hour surface period. Only flag byte 2 is sent in the data messages, as part of message number 1. Bit one is set for each deep profile and bit 8 is set each time the last SBE sensor value used an arithmetic round up.

Below is a list of what each bit in each byte signifies.

bit  
Flag (2) byte: 1 Deep profile  
2 Pressure reached zero  
3 25 minute NextP timeout  
4 Piston fully extended  
5 Ascend timed out  
6 Test message at turn on  
7 Six hour surface message  
8 Seabird string length error

bit  
Flag (1) byte: 1 Trip interval time  
2 Profile in progress  
3 Timer done (2 min bladder deflate time.)  
4 UP/DOWN  
5 Arithmetic round up  
6 Measure battery while pumping  
7 Piston motor running  
8 Negative SBE number

The flag bytes are transmitted as two hex characters with four bits of information encoded in each character. Each hex character can have one of 16 different values as shown in the following table.

1	0	0000	10	9	1001
2	1	0001	11	A	1010
3	2	0010	12	B	1011
4	3	0011	13	C	1100
5	4	0100	14	D	1101
6	5	0101	15	E	1110
7	6	0110	16	F	1111
8	7	0111			
9	8	1000			

Bit 8 is the most significant bit and bit 1 is the least significant bit in the byte.

As an example: if a deep profile ended with the piston fully extended and ascend had timed out, then bits 1, 4 and 5 would be set in the termination byte. This binary pattern, 0001 1001, would be transmitted as the two hex characters, 19.

As another example: if a regular profile ended with the piston fully extended and the 25 minute next pressure had timed out, then bits 3 and 4 would be set in the termination byte. This binary pattern, 0000 1100, would be transmitted as the two hex characters, 0C.

## Appendix B: CRC Algorithm in BASIC for 28 bit Id

Below is a sample program (in BASIC) to calculate the CRC value for a message. This program can be provided upon request in Basic, Fortran or C.

```
DECLARE FUNCTION CRC% (IN() AS INTEGER, N AS INTEGER)
'CRC routine to check data validity in ARGOS message.
'Bathy Systems, Inc. RAFOS Float data transmission.
'3 December, 1990.
'The 1st of 31 bytes in an ARGOS message is the CRC.
'The function CRC will compute CRC for byte 2 through 31.
'Hasard is used for Random because Random is reserved by BASIC.
'Stored as file CRC in C:\RAFOS\RAF11.
DECLARE SUB Hasard (ByteN AS INTEGER)
DEFINT A-Z
DIM in(31) AS INTEGER
'RAF11F message number 08 HEX ID 11502 01-02-93 CRC is O.K.
A$ = "d802075d87c64e15078187c64c1f07b287c74a3007ce87c6483f07fe87c246"
  N = 31
  FOR I = 1 to N
    in(I) = VAL("&H" + MID$(A$, 2 + I - 1, 2))
  NEXT I
  PRINT in(1); CRC(in(), N);

FUNCTION CRC% (IN() AS INTEGER, N AS INTEGER) STATIC
DIM ByteN as INTEGER
  I = 2
  ByteN = in(2)
  DO
    CALL Hasard(ByteN)
    I = I + 1
    ByteN = ByteN XOR in(I)
  LOOP UNTIL I = N
  CALL Hasard (ByteN)
  CRC = ByteN
END FUNCTION

DEFINT A-Z
SUB Hasard (ByteN AS INTEGER) STATIC
x% = 0
  IF ByteN = 0 THEN ByteN = 127: EXIT SUB
  IF (ByteN AND 1) = 1 THEN x% = x% + 1
  IF (ByteN AND 4) = 4 THEN x% = x% + 1
  IF (ByteN AND 8) = 8 THEN x% = x% + 1
  IF (ByteN and 16) = 16 THEN x% = x% + 1
  IF (X% AND 1) = 1 THEN
    ByteN = INT(ByteN / 2) + 128
  ELSE
    ByteN = INT(ByteN / 2)
  END IF
END SUB
END SUB
```



## Appendix C: Surface arrival time, and total surface time

Some users may wish to determine surface arrival time, and total surface time, in order to calculate drift vectors.

Although each 31-byte message is time-stamped by ARGOS, there may not be a satellite in view when the float surfaces.

When the float surfaces (ie detects surface pressure recorded before last descent) it will begin ARGOS telemetry. Messages are transmitted in numerical order, starting with message no. 1. When all messages have been transmitted, the cycle starts again at message no. 1.

### Elapsed time since surfacing ( $T_e$ )

$$T_e = (m-1)*n*r$$

Where:  $m$  = message block number (byte 03 of message 01)

$n$  = total number of messages to transmit profile

$r$  = repetition rate

Total number of messages ( $n$ ) is described in section IV (b), or may be determined from the ARGOS data. Note ( $n$ ) may be less than specified in user manual if the float is operating in shallow water, causing reduced profile length.

Repetition rate ( $r$ ) is the time interval between ARGOS transmissions. This value can be determined from section V, or from the ARGOS data.

### Approximate time of surfacing

Subtracting  $T_e$  from the ARGOS time stamp can determine approximate time of surfacing

#### Example

Below is message 01 in DS format

```
2001-11-02 22:47:54 1 CF 01 05 02
AF 02 2F 00
85 01 01 01
16 92 17 19
9E 94 01 AD
85 09 1F 48
97 9B 00 46
62 24 0E
```

$m$  = message block number (byte 03) = 5

$n$  = total number of messages to transmit profile = 11

$r$  = repetition rate = 62 seconds

**Te** = elapsed time since surfacing =  $(m-1)*n*r = (5-1)*11*62 \text{ s} = 2728 \text{ s} = 00\text{h } 45\text{m } 28\text{s}$

Approximate time of arrival at surface:

ARGOS time stamp - Te = 22:47:54 - 00:45:28 = 22:02:26

Total time spent at surface transmitting (Tsurf):

This is determined by subtracting ascent time from UP time.

$T_{\text{surf}} = (\text{UP time, hr}) - (\text{bottom pressure})/(\text{ascent rate } 0.08 \text{ dbar/s})/3600$

Bottom pressure is telemetered as bytes 7 & 8 of message 02.

Example:

For bottom pressure of 2000 dbar, and UP time of 18 hours

$T_{\text{surf}} = (18 \text{ hr}) - (2000/0.08/3600) = 11 \text{ hr}$

## **APPENDIX D: Argos ID formats, 28 bit and 20 bit**

In 2002 Service Argos notified its users there were a limited number of 20-bit Ids available and to begin preparing for a transition to 28-bit IDs. The 28 bit-IDs reduced from 32 to 31 the number of data bytes in each message. Data provided by Argos will consist of 31 hex bytes per message. Data acquired by use of an uplink receiver will consist of 32 hex bytes per message. The first byte, when using an uplink receiver, is a 28-bit ID identifier used by Argos and is not represented in the Apex Data formats included in this manual.

## **APPENDIX E: Storage conditions**

For optimum battery life, storage temperature range is +10 to +25 degrees C. When activated, the floats should be equilibrated at a temperature between -2 and +54 degrees C. If optional VOS or aircraft deployment containers are used, these must be kept dry, and should be stored indoors only.

## **APPENDIX G Returning APEX for factory repair or refurbishment**

Contact WRC before returning APEX floats for repair or refurbishment.

All returns from outside USA, please specify our import broker:

Logan International Airport, Boston

c/o DHL-Danzas Freight Forwarding Agents,

Phone (617) 886-5605, FAX (617) 241-5917

500 Rutherford Avenue, Charlestown, MA 02129

Note on shipping documents: US MADE GOODS

**APPENDIX G: CTD Calibration and Ballasting records**  
**(included in hard copy only)**